4008 HDF

Technical Manual



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The Technical Manual contains all information necessary for performing maintenance and repair work.

The 4008 HDF option reflects the latest state of technology and complies with the requirements of EN 60601-1

Assembly, extension, adjustment, modification or repair may only be carried out by the manufacturer or persons authorized by him.

Any inquiries should be addressed to:

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Local Service:

How to use the Technical Manual

Search and find What? Where?

Tables Contents Pages 0-5 and at the beginning of each chapter

Purpose This manual is intended for:

first studies (to acquire basic knowledge)

reference purposes (for start-up, maintenance and repair)

Organization The manual is divided into 6 chapters:

0 General Notes

1 Description of machine functions

2 Technical safety checks3 Calibration instructions

4 Circuit descriptions and circuit diagrams

5 Spare parts

Numbering system Page number 1-3 is to be interpreted as: Chapter 1, Page 3

Qualification This manual is intended for service technicians

who are familiar with the current Operating Instructions (Operating Instructionseratining to this Technical Manual are available under part no. 674 406 1)

 who have the necessary background experience in mechanics, electrical and medical engineering

 who have been authorized by the manufacturer to perform maintenance and repair work

who have access to the necessary auxiliary and measuring equipment

Restrictions The study of this manual does not represent an alternative to the training courses

offered by the manufacturer.

Manual changes Manual changes will be released as new editions, supplement sheets or product

information.

Note:

Modifications relating to circuit diagrams and component layouts (SP/BP) do not

necessarily involve a change of the footer (edition).

Refer to the index field of the respective circuit diagram or component layout for the respective state of these diagrams. The identification on the P.C.B. permits the user/technician to verify if the circuit diagram / component layout matches the

P.C.B. actually installed.

In general, this manual is subject to modification.

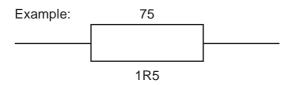
Representation

New circuit symbols are used in the circuit diagrams. Potential data given in the circuit diagrams and setting instructions refer to the respective earth.

For account and the second second for 04 V colleges

For example: <u>L</u> 24 means ground for 24 V voltage.

Component marking in circuit diagrams



This refers to a resistor with a position number 75 with a resistance of 1.5 Ohm.

The decimal point is replaced by a unit symbol (to reduce the possibility of errors).

Resisto	ors:	Capacito	Capacitors:		
R1:	0.1 Ω	μ1:	0.1 μF		
1R5:	$1.5~\Omega$	1μ5:	1.5 μF		
1K5:	$1.5~\mathrm{k}\Omega$	1000μ:	1000 μF		

Note:

When repairing or exchanging replacement parts make sure to take the applica-

ble ESD precautions (e.g. EN 100 015-1).

During repair/troubleshooting in the hydraulic unit, protect the components from

dialysate.

Technical data:

The technical data for the 4008 HDF option is to be found in Chapter 1 of the

Operating Instructions.

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Table of contents 1 Description of machine functions

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1.1 Description

1.1.1 Components

The components of the 4008 HDF option are permanently connected to the hemodialysis machine. The 4008 HDF option comprises the following components:

- Substituate lift
- Scales (weighing range < 20 kg) with data interface and taring facility
- Substituate pump with bidirectional data interface
- UF2 pump

1.1.2 Description

The scales determine the actual weight of the substituate reserve and signals this to the hemodialysis machine. This calculates the substituate rate depending on the set treatment time.

A substituate sensor mounted on the substituate lift recognises whether:

- Line set is fitted without substituate or
- Line set is fitted with substituate.

The substituate pump delivers the substituate solution to the venous bubble catcher. The filtrate from the dialysis fluid circuit is removed by the UF2 pump.

1.1.3 Component tests

The scales are checked by the operator by means of a plausibility test before treatment. The substituate sensor is tested while the 4008 HDF is filling.

The 4008 HDF test tests:

- The substituate pump
- The UF2 pump (electrically and hydraulically)

(If the 4008 HDF test is not carried out then the connections are to be tested but once).

The UF2 pump is tested cyclically during treatment.

The electric control system of the UF2 pump is checked continuously.

Fig.: Block diagram

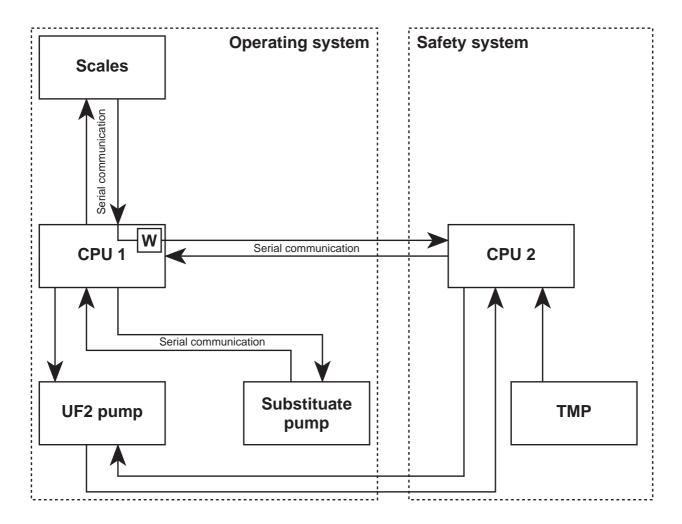


Fig.: Flow diagram

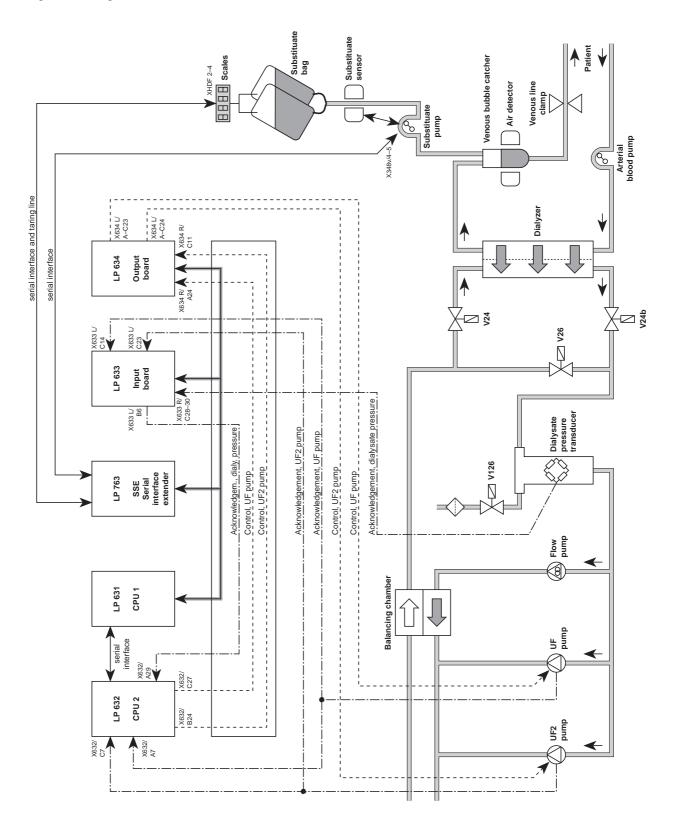
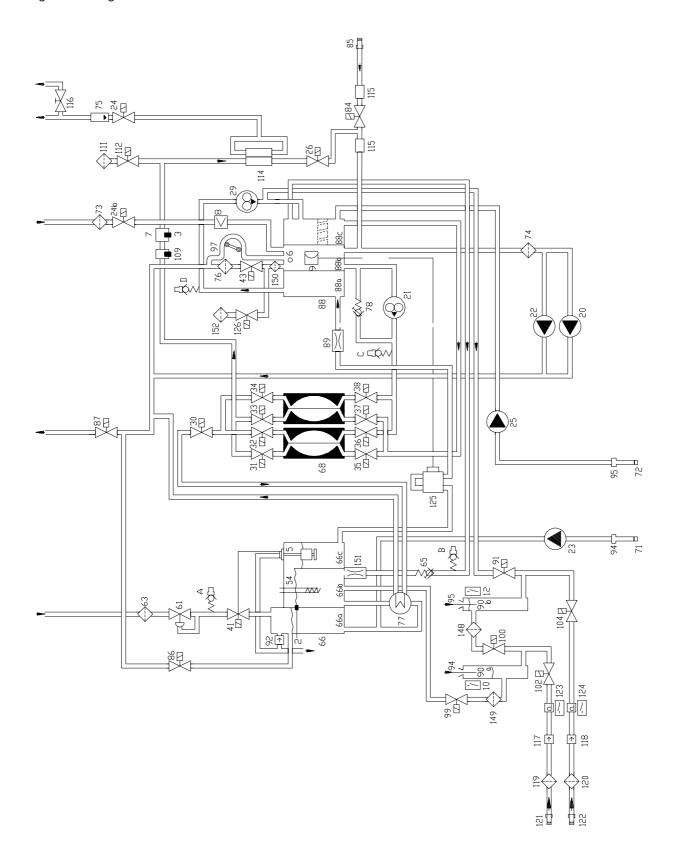


Fig.: Flow diagram



Legend

2 Temperature sensor

3 Temperature sensor

5 Float switch

6 Level sensor

7 Conductivity measuring cell

8 Blood leak detector

9 Pressure transducer

10 Reed contact for concentrate

12 Reed contact for bicarbonate

20 UF2 pump

21 Flow pump

22 UF pump

23 Concentrate pump

24 Dialyzer valve 1

24b Dialyzer valve 2

25 Bicarbonate pump

26 Bypass valve

29 Degassing pump

30 Drain valve

31 Balancing chamber valve 1

32 Balancing chamber valve 2

33 Balancing chamber valve 3

34 Balancing chamber valve 4

35 Balancing chamber valve 5

36 Balancing chamber valve 6

37 Balancing chamber valve 7

38 Balancing chamber valve 8

41 Water inlet valve

43 Fill valve

54 Heater rod

61 Pressure reducing valve

63 Filter/water inlet

65 Loading pressure valve

66 Heater block

66a Water inflow chamber

66b Heater rod chamber

66c Float chamber

68 Balancing chamber

71 Filter/concentrate

72 Filter/bicarbonate

73 Filter/external dialysate

74 Filter/UF

75 External flow indicator

76 Filter/fill valve

77 Heat exchanger

78 Relief valve

84 Disinfection valve

85 Disinfectant conncector

86 Recirculation valve

87 Discharge valve

88 Multifunction block

88a Degassing chamber

88b Secondary air separator

88c Primary air separator

89 Degassing orifice

90a Rinse chamber concentrate

90b Rinse chamber bicarbonate

91 Rinse valve

92 Vent valve

94 Concentrate suction tube

95 Bicarbonate suction tube

97 Ventilation pump

99 Rinse valve

100 Rinse valve

102 Concentrate valve in central delivery system

104 Bicarbonate valve in central delivery system

109 Temperature sensor

111 Hydrophobic filter

112 Vent valve

114 Dialysate filter

115 Disinfection valve sensor

116 Sampleing valve

117 Check valve (concentrate)

118 Check valve (bicarbonate)

119 Filter (concentrate)

120 Filter (bicarbonate)

121 Concentrate connector in central delivery system

122 Bicarbonate connector in central delivery system

123 Pressure switch for V 102

124 Pressure switch for V 104

125 Adapter plate

126 4008 HDF vent valve

148 Filter/rinse valve

149 Filter/rinse valve

150 Filter

151 Orifice

152 4008 HDF hydrophobic filter

Hydraulic measurement points

- A Reduced water inlet pressure
- B Balancing chamber loading pressure
- C Flow pump pressure
- D Degassing pump pressure

1.2 Description of extended T1 test / error messages in the T1 test

Possible error messages displayed in the T1 test are listed in the Technical Manual for the hemodialysis machine. If the HDF option is installed and activated the following error codes can also appear:

1.2.1 Test UF-Function

Test description:

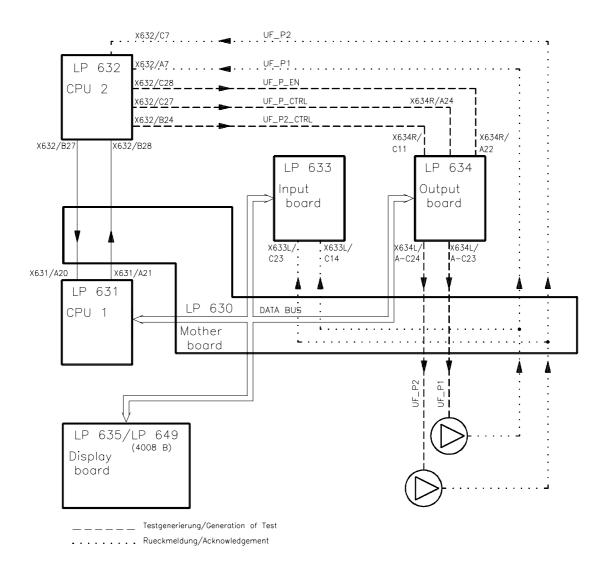
CPU 1 starts up the UF2 pump at a defined rate.

CPU 2 controls the hydraulic and electrical function of the UF2 pump.

CPU 2 blocks the control line of the UF2 pump and checks for standstill.

UF2 counter check.

Figure:



Error description:

Error message Description

F11 UF-Function The interval between the strokes of the UF2 pump was less than

220 ms. Correct delivery of the required volume is not safeguard-

ed because the stroke return travel is too short.

A pump rate which was too high was signalled by the CPU 1.

F12 UF-Function The pulse time for the UF2 pump is less than 180 ms. Correct

delivery of the required volume is not safeguarded because the

discharge time is too short.

- Monoflop on LP 634 defect (IC 42/R65/C45).

F 13 UF-Function The pulse for the UF2 pump is longer than 500 ms. A maximum

rate of 5000 ml/h is not possible.

- Monoflop on LP 634 defect (IC 42/R65/C45).

F14 UF-Function UF2 pump not active during the test (4 s).

Acknowledgement (UF_P2, X637/B26) → X632/C7 no LOW

pulse

- Control line (UF_P2, X634L/A-C24) \rightarrow X637/B26 no LOW

pulse

F15 UF-Function The UF2 pump cannot be stopped by the CPU2.

- Control line (UF_P_EN, X632/C28) \rightarrow X634R/A22 no 5 V.

Reset input to IC 42/pin 13 on LP 634 defect.

F16 UF-Function The UF pump acknowledgement from CPU1 is faulty.

Acknowledgement (UF_P2, X637/B26) → X633/C23 no LOW

pulse

F17 UF-Function The change in pressure after a UF2 pump stroke less than

20 mmHg.

- UF2 pump mechanically defect.

- Control line (UF_P2_CRTL, X632/B24) → X634R/C11 no

HIGH pulse.

F20 UF-Function Difference in pressure between UF pump stroke and UF2 pump

stroke more than 20 %.

Stroke rate for UF pump or UF2 pump not set correctly.

Error messages during treatment and the HDF test 1.3

Message on the display	Cause	Possible error elimination
F321 HDF-failure	The UF pump or UF2 pump test will not be started as long as the level sensor (6) detects air. The level sensor (6) will detect air one minute after the 4008 HDF test has been selected	Check level sensor (6) (defect).
F322 HDF-failure	The UF pump or UF2 pump has carried out more than 50 strokes and still no air has been detected.	Check V126 (does not open, venous bubble catcher collapses), check V43 (whether leaking or open). Check UF pump or UF2 pump, respectively (mech. defect).
F323 HDF-failure	The substituate pump runs at a rate of 10 ml/min. to raise the fluid level by a defined amount in the secondary air separator (the fluid will just be detected). Air will still be detected after 2 minutes.	Check substituate tubing (clamped off, not connected to the venous bubble catcher).
F324 HDF-failure	Since fluid has been recognized in the secondary air separator the substituate pump starts at a rate of 10 ml/min. until a change in weight follows on the scales (i.e. a jump in grammes). There was no difference in weight established after one minute.	Check substituate tubing (clamped off).
F325 HDF-failure	If the expected change in weight (i.e. a jump in grammes) is higher or lower than –1 g, the respective UF pump test will be repeated. The UF pump test was repeated more than 5 times.	Check bag (fluctuations in air draft) Check scales (for drifting).

Message on the display	Cause	Possible error elimination
F326 UF-failure	The fluid level in the secondary air separator is raised again by the substituate pump after 100 strokes of the UF pump or UF2 pump, respectively, until fluid is detected. Plus run-on time at a rate of 10 ml/min. for the gramme jump. Air will still be detected after a specific period of time (depending on the delivery rate of the substituate pump).	Check substituate hose (clamped off, not connected with the venous bubble catcher).
UF1 volume-Error or UF2 volume-Error	One UF pump did not pass the test. The filling volume for the secondary air separator is not within the given tolerance of 100 ml; ± 5 ml. Should the test give a reading of over 105 ml the cause could also be air taken in the flow from a badly vented dialysator.	Check UF pump or UF2 pump, respectively (not calibrated, mechanical defect).
F327 UF-failure	Interval between two strokes of the UF pump less than 220 ms.	Check CPU 1 (defect).
F328 UF-failure	Pulse time of a stroke of UF pump less than 180 ml.	Check LP 634 (regulating monoflop defect).
F329 UF-failure	Pulse time of a stroke of UF pump more than 500 ms.	Check LP 634 (regulating monoflop defect).
F330 UF-failure	Starting time for the UF pump more than 10 seconds.	Check LP 634 (regulating end stage defect).
F331 UF-failure	Difference between desired or actual delivery rate of the UF pump greater than ± 10%.	Check CPU 1 / CPU 2 (communication problems).
F332 UF-failure	UF pump stops longer than the maximum period time.	Check LP 634 (regulating end stage defect). Check UF pump (interruption, control). Check CPU 1 / CPU 2 (communication problems)
F333 UF-failure	Despite switched off ultrafiltration the change in delivery rate of the UF pump is greater than 10 ml.	Check CPU 1 / CPU 2 (communication problems)
F334 UF-failure	Interval between two strokes of the UF2 pump less than 220ms.	Check CPU 1 (defect).

Message on the display	Cause	Possible error elimination
F335 UF-failure	Pulse time of a stroke of the UF2 pump less than 180 ms.	Check LP 634 (regulating monoflop defect).
F336 UF-failure	Pulse time of a stroke of the UF2 pump more than 500 ms.	Check LP 634 (regulating monoflop defect).
F337 UF-failure	Reaction time of the UF2 pump more than 10 seconds.	Check LP 634 (regulating end stage defect).
F338 UF-failure	Difference in desired or actual delivery rate of UF2 pump greater than ± 10 %.	Check CPU 1 / CPU 2 (communication problems).
F339 UF-failure	UF2 pump stops longer than the maximum period time.	Check LP 634 (regulating end stage defect). Check UF pump (interruption, control). Check CPU 1 / CPU 2 (communication problems).
F340 UF-failure	Despite switched off 4008HDF change in delivery rate of the UF2 pump greater than 10 ml.	Check CPU 1 / CPU 2 (communication problems).
F341 UF-failure	Failure of UF pump.	Check UF pump (spring, screen)
F342 UF-failure	Failure of UF2 pump.	Check UF2 pump (spring, screen)
F343 UF-failure	Volume difference between UF pump and UF2 pump.	Check UF pump and UF2 pump (delivery volume)
F344 HDF-failure	Balance failure recognized by CPU2 greater than ± 500 ml.	Check monitor / scales (communication problems).
F345 HDF-failure	Bolus exceeded by more than + 20 ml, detected by CPU2.	Check monitor / scales (communication problems).
F346 HDF-failure	CPU2 failed to perform the cyclic UF pump test within 5 minutes.	Check V24B and V43 feed-back lines. Check sense of rotation of aspiration pump. Check hydraulics unit for leaks.
F348 HDF-failure	Weight change on the scales during the weighing test greater than 2g.	Check scales Check substituate bag
F349 HDF-failure	The delivery rate correction factor could still not be determined after 20 minutes treatment time.	Check substituate bag (weight fluctuations) Check HDF control system (greater fluctuations)

Error messages, substituate pump 1.4

Code	Description of failure
E.01	Line diameter outside the permitted range
E.02	Non-defined hexaswitch position
E.03	Venous pressure transducer not balanced
E.04	Failure, running time monitoring system, SN operation
E.05	SN stroke volume outside the permitted range
E.06	The SN pressure thresholds outside the value range of the AD converter
E.07	Not defined
E.08	Failure in the AD conversion
E.09	Not defined
E.10	Not defined
E.11	Not defined
E.12	Failure, speed monitoring (hall sensor)
E.13	Failure, monitoring system, current sensing resistors
E.14	Failure, monitoring system, current sensing resistors
E.15	Failure, speed monitoring system

2 Technical safety checks

General Notes

This chapter includes all necessary technical safety checks (TSC).

These inspections must be carried out every 12 months.

The technical safety inspections stipulated for the hemodialysis machine must be carried out in addition to these technical saftey checks.

The technical safety checks are to be recorded in the equipment log.

A technical safety checks report is to be found at the page 2-3.

Technical s	afety che	cks report
-------------	-----------	------------

Manı	ufactu	rer:		Date:		
Mach	nine:			Technician:		
Oper	ating	hours:				
		١	Extent of checks and time lim	ts for technical safety	checks.	
			TIME LIMIT: ex	ery 12 months		
mont a res instr	ths by ult of uction	persor their tra s as to	cks and inspections have to be nowns who are capable of carrying aining, knowledge and experion their checking activity. Illetin dated 02.04.1987)	out such technical sa	afety checks efficientl	y as
T00	14/4		De a saladia a	Desire Leveley (for all		01/
TSC	WA	No.	Description	Desired value/function	on	ок
T00		1	UF2 pump	00 / 1 00 1 / 4	0/	
TSC		1.1	Delivery volume (1 ml/stroke)	60 strokes = $60 \text{ ml} \pm 1$	%	
		2	VDE inspections (values acco	ording to EN 60601-1)		
TSC		2.1	Protective ground resistance	max. 0.3 Ω		
TSC		2.2	Summarized leakage current	Must fulfill both conditi 1. No more than 1.5 ti zed value first mea: ("Summarized value Refer to the machine the machine.) 2. No more than 1 mA	imes the "summari- sured" e first measured": ne card enclosed with	
The technical safety checks are to be recorded in the equipment log and the results of the checks documented. If the machines are not safe in function and/or operation they are to be repaired or the operator is to be informed as to the dangers involved when using the machine in its given state.						
The correct completion of the listed work and the correctness of statements made are hereby certified.						
Signa	Signature, technician: Signature, customer:					
	, date, date,					

Table of contents 3 Calibration instructions

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3.5 3.5.1 3.5.2	Calibrating the HDF blood pump Pressure transducer Checking SN switchover points	3-15 3-15 3-16
3.6	Repair instructions	3-17

3.0 General information on the calibration instructions

Measuring instruments:

The same measuring instruments as used for the hemodialysis machines are to be employed. Required in addition is a calibration weight PT6 - 5000 g.

Fig.: P.C.B. overview 4008 HDF

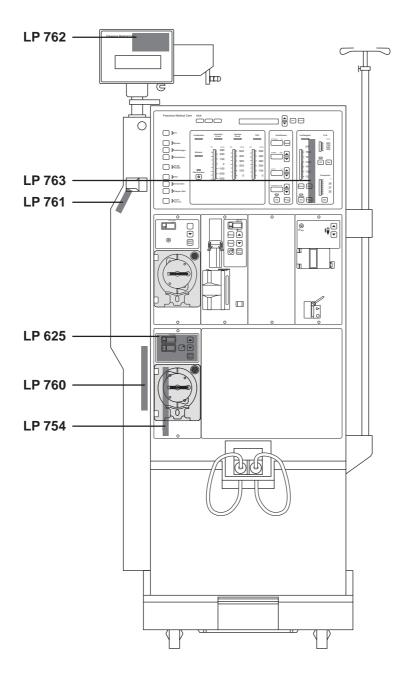
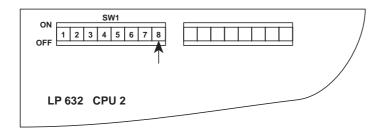


Fig.: DIP switch 4008 HDF

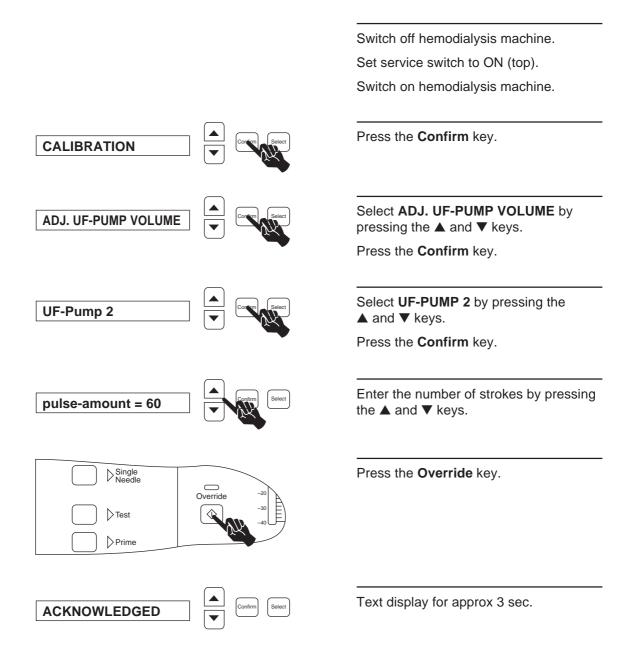


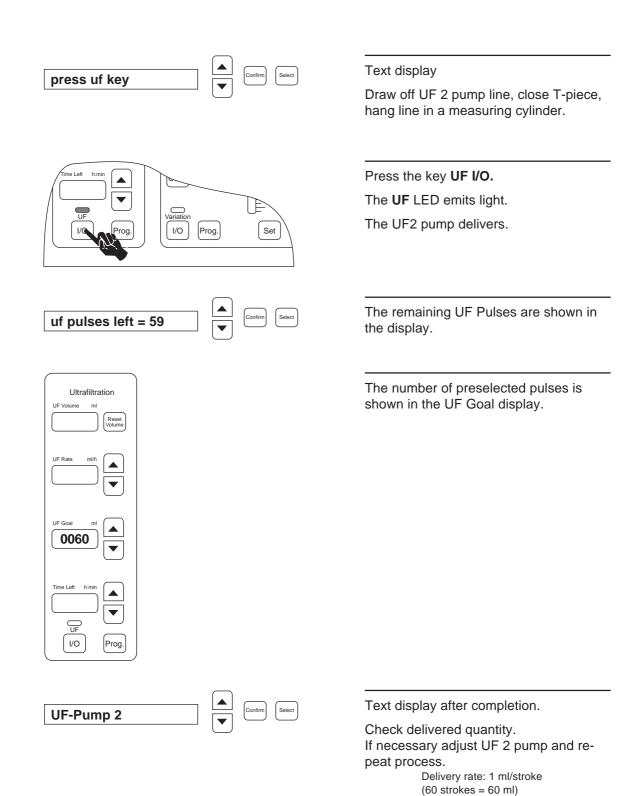
SW 1, DIP switch 8:

ON: 4008 HDF test selectable (required/not required)

OFF: 4008 HDF test carried out automatically

3.1 Calibrating the UF2 pump



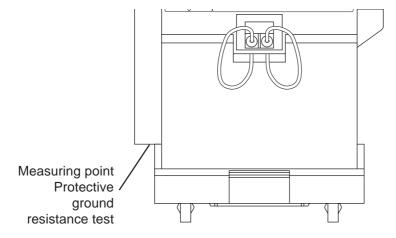


Tolerance: ± 1 %.

3.2 VDE inspections

(Values in accordance with EN 60601-1)

- .1 Protective ground resistance:
- max. 0.3 Ω.



.2 Summarized leakage current

Must fulfill both conditions:

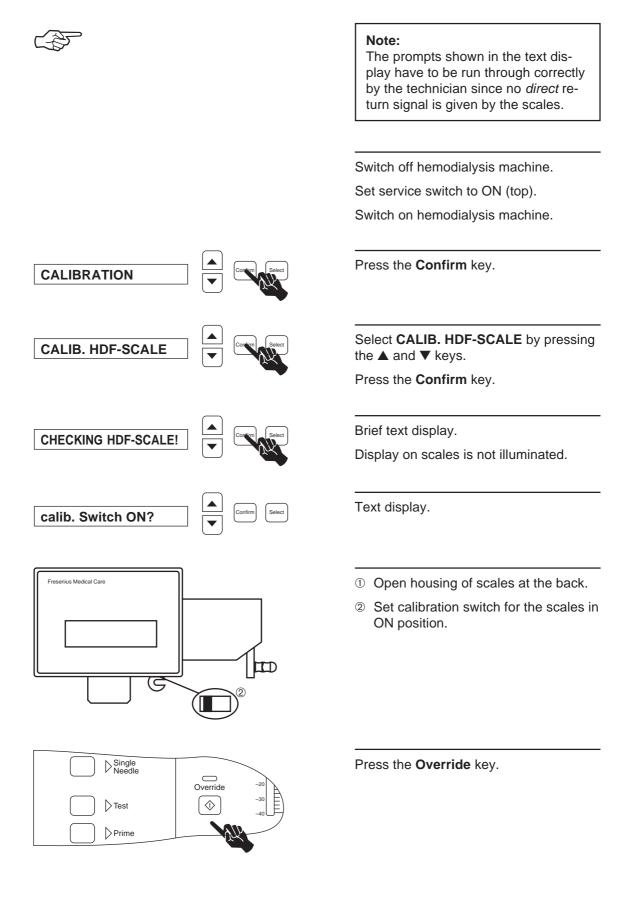
- No more than 1.5 times the "summarized value first measured" ("Summarized value first measured": Refer to the machine card supplied with the machine.)
- 2. No more than 1 mA

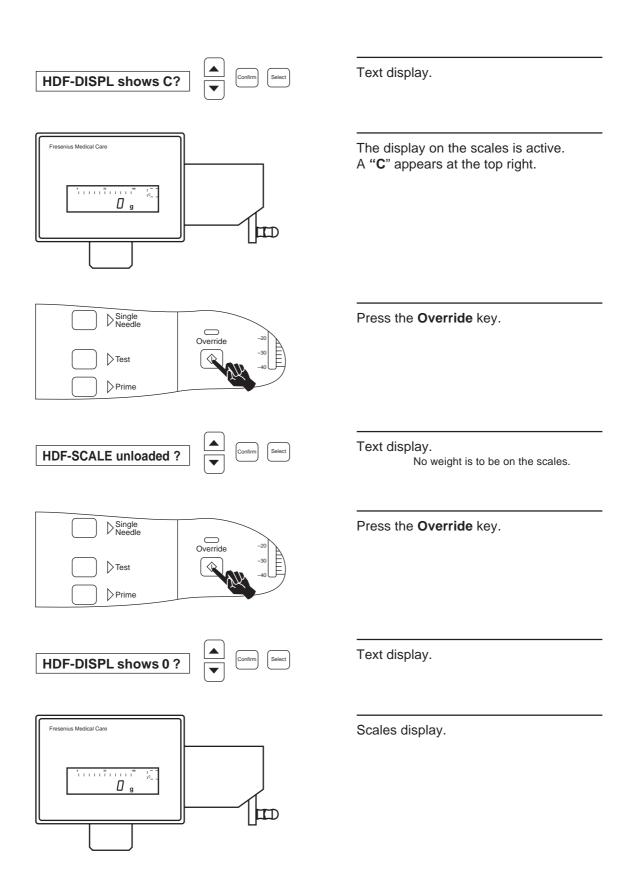
The measurements must be taken in the dialysis mode of operation in the "ON phase" of the heating control system.

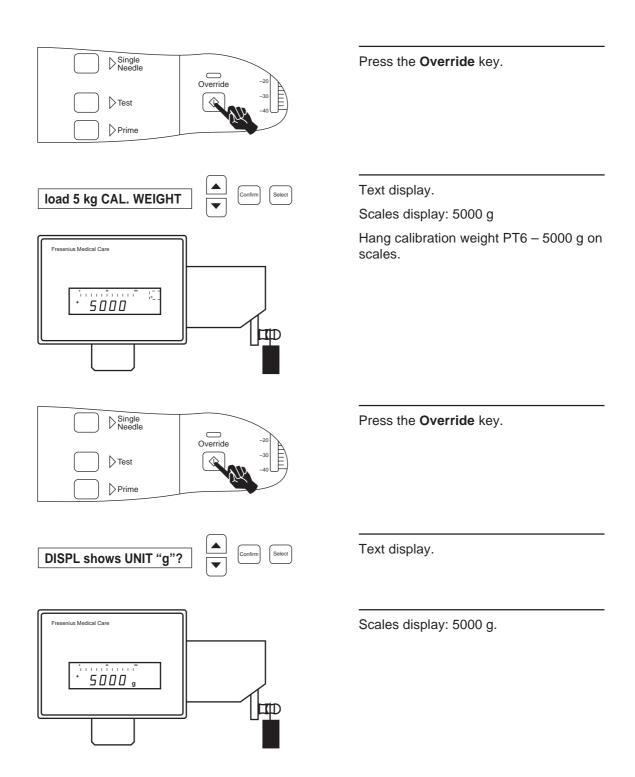
The scales must be travelled out to such an extent that neither of the two end switches are actuated (middle position).

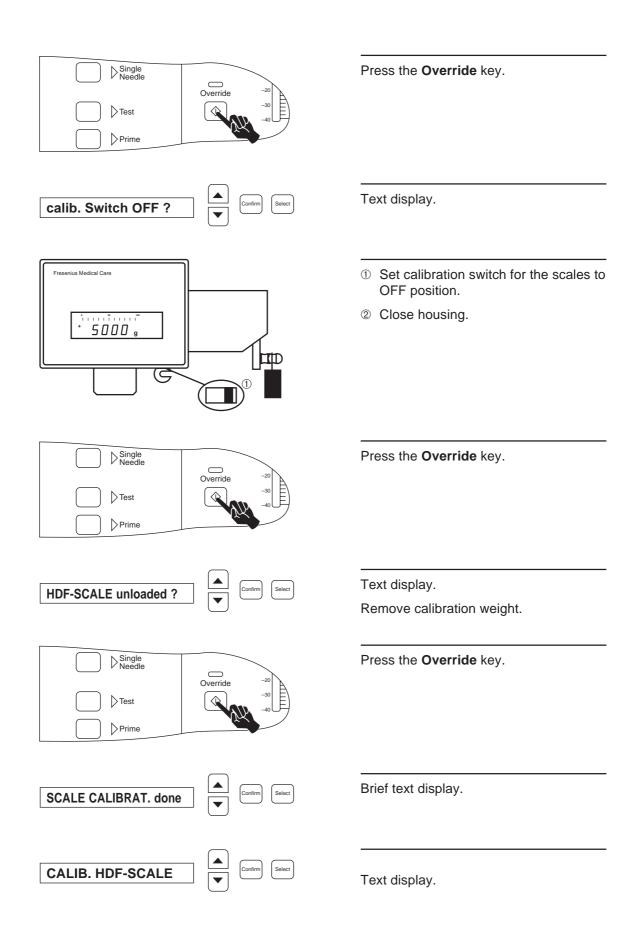
The two leakage currents are to be measured each time with different mains connection poling. The two leakage currents are added together and give the summarized leakage current.

3.3 Calibrating the 4008 HDF scales







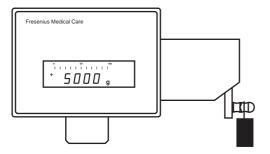


Switch off hemodialysis machine.

Set service switch to OFF (bottom).

Switch on hemodialysis machine.

Hang calibration weight PT6 – 5000 g on scales.

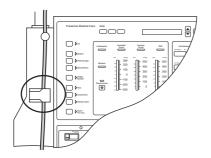


Scales display: 5000 g

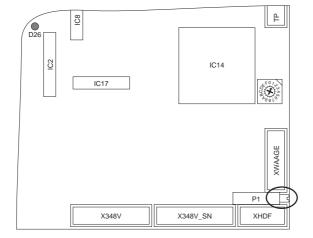
Remove calibration weight.

Calibration of 4008 HDF scales completed.

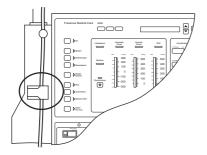
3.4 Calibrating the substituate sensor



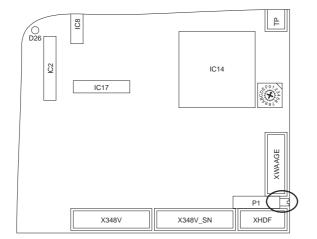
Place filled substituate line in substituate sensor.



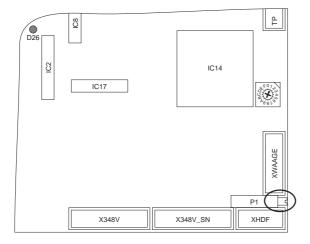
Set potentiometer P1 on the LP 754 so that the LED D26 just illuminates.



Place empty substituate line in substituate sensor.



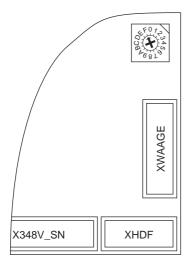
Adjust potentiometer P1 on LP 754 until LED D26 just turns off.
Count the number of revolutions the potentiometer is turned. Keep this number in your mind.



Turn back the potentiometer P1 on the LP 754 by half this number.
The LED D26 will illuminate again.

3.5 Calibrating the HDF blood pump

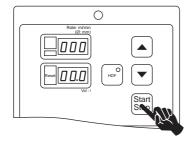
3.5.1 Pressure transducer



Switch the hemodialysis machine off.

Set HEX switch on the LP 754 to position "F".

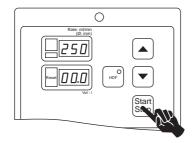
Switch the hemodialysis machine on.



Display 000

Open SN pressure transducer to atmosphere.

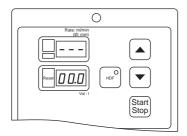
Press the **Start/Stop** key.



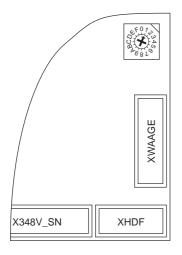
Display 250

Apply a pressure of 250 mmHg to the SN pressure transducer.

Press the **Start/Stop** key.



Display ---



Switch off hemodialysis machine.

Set HEX switch on the LP 754 to position 1.

Balancing out has been completed.

3.5.2 Checking SN switchover points

Bottom switchover point: fixed at 75 mmHg (± 6 mmHg)

Top switchover points (± 6 mmHg):

Stroke volumes (ml)	10	15	20	25	30	35	40	45	50
Top switchover point	110	130	150	172	195	219	244	270	299

3.6 Repair instructions



Important:

If the substituate lift has to be dismounted for repair the seal is to be checked and if necessary renewed before fitting the lift again.

Drip water protection!

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4 Circuit descriptions and circuit diagrams

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Fig.: Connection diagram 4008 HDF

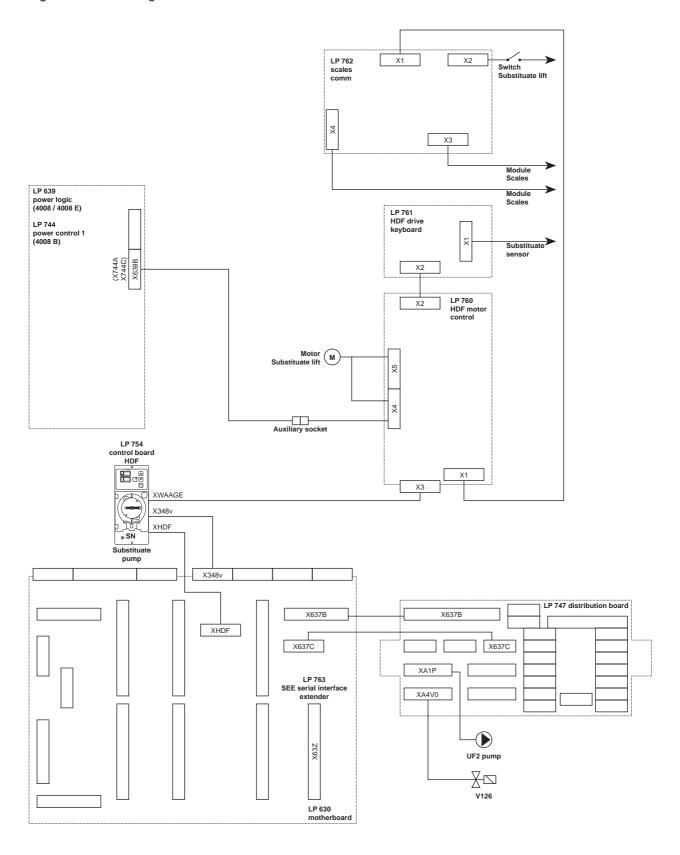


Fig.: Wiring diagram 4008 HDF

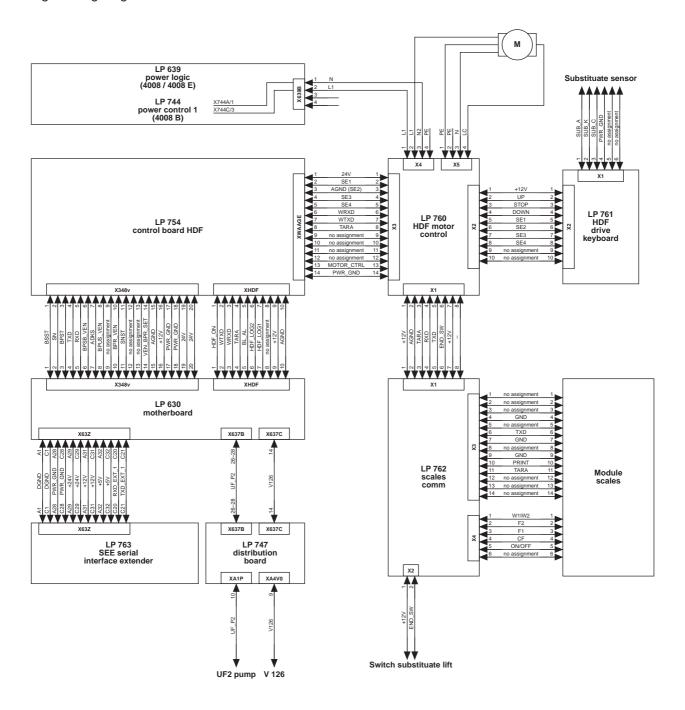


Fig.: Block circuit diagram, mains voltage 4008 HDF

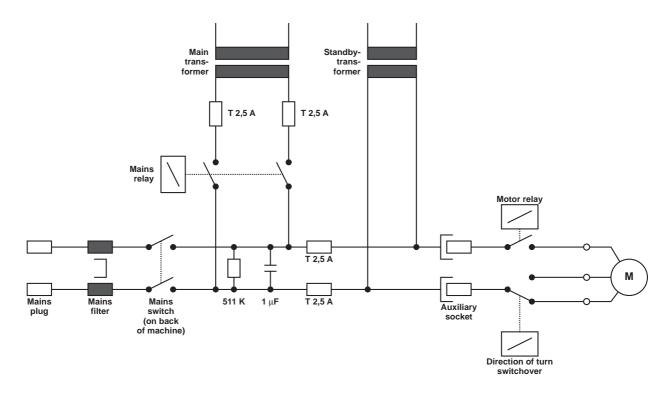
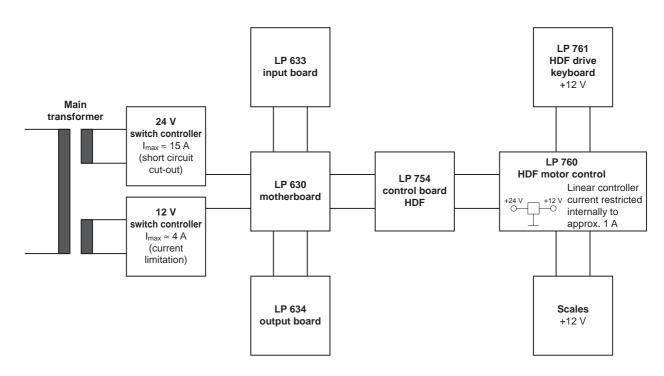


Fig.: Block circuit diagram, low voltage 4008 HDF



4.1 LP 625 display board

4.1.1 Description

General

The displays and the keyboard are on this P.C.B..

Plug connections to LP 625:

- X189, connection to LP 760

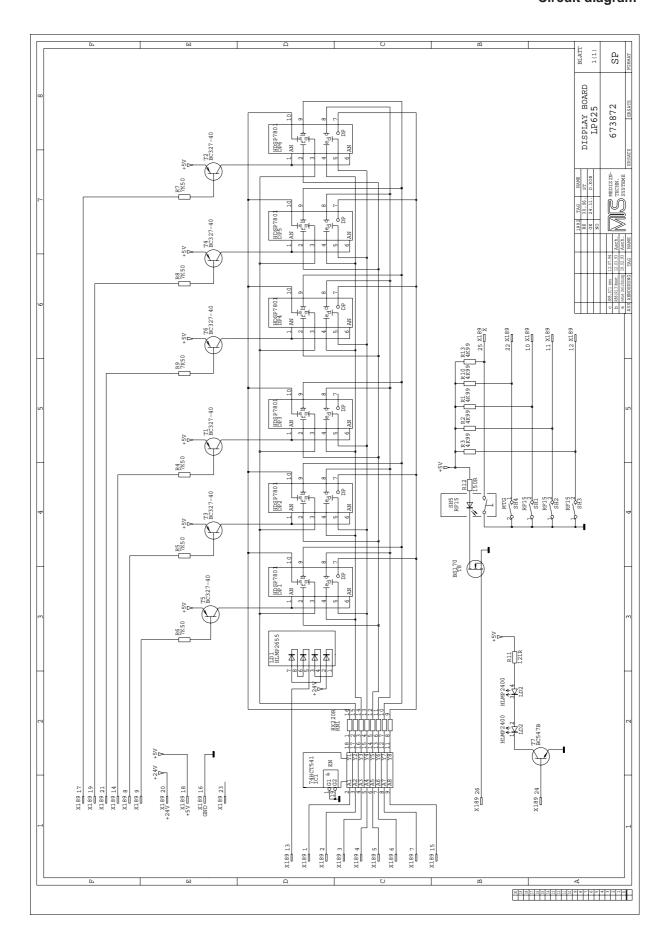
Display

All necessary information is given to the user through 6 multiplex 7-segment displays and 2 LEDs which are mounted on the socket.

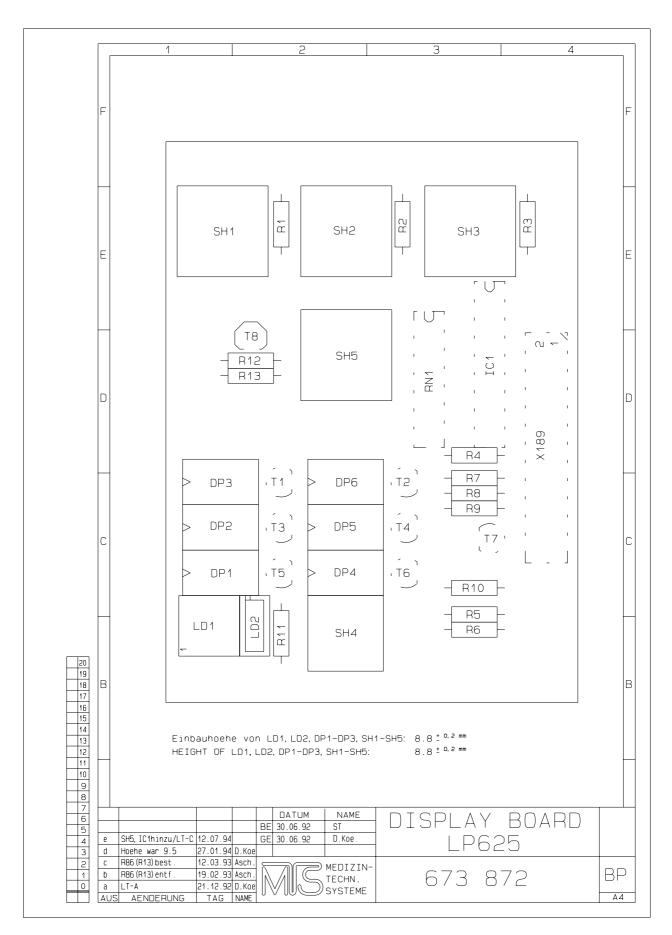
Keyboard

The keyboard comprises 3 single non-illuminated keys and 1 key with integrated LED (HDF). The keys are soldered directly to the P.C.B..

The user receives a acknowledgement through a spring contact when the keys are pressed.



LP 625
Component layout diagram



4.2 LP 754 control board HDF

4.2.1 Description

General

The control, section and power pack are on the this P.C.B..

Plug connections to LP 754:

- X186, connection to position sensor
- X188, connection to stepper motor
- X189, connection to LP 748
- X190, connection to cover switch
- X192, connection to pressure transducer
- X348, connection to dialysis monitor

Hexswitches on the LP 754:

- 0 No function
- 1 Single needle blood pump / 4008 HDF / ON LINE HDF
- 2 A No function
- B Blood pump stop alarm (15, 30 secs.)
- C No function
- D Call-up operating time meter (display x 100 = number of hours)
- E Test operation (only manufacturer)
- F Pressure transducer calibration

Voltage generation

The +24 V and +12 V voltage supply is made available to the blood pump by the monitor. The +5 V supply voltage is generated on the module by the switch controller IC 20 from the +24 V voltage to minimize loss of power.

• Stepper motor control

The stepper motor is run in microstep operation to reduce noise. The resolution is 60 microsteps per step. The RISC processor transmits a 8-bit dataword alternately on the pins 3 and 5 of the DA converter from IC 7. Two sine form voltages are available on the output of the converter, phase offset by 90°. They are conducted to the stepper motor controller IC 2 together with the current direction signals. Together with the two SM drivers IC 1/IC 22 and the current sensor resistors R58/R59 as feedback these form a closed control circuit which determine two sine-shaped currents, phase offset by 90°, in the two coils.

Microprocessor

The cycle frequency of the microprocessor is determined by the quartz Q2 between the processor connections 39 and 40. Quartz oscillation is made possible by the capacitors C5 and C6.

The keyboard signals and the signals BSST, BPST are read-in through the port P4.

The IC 9 serves as intermediate memory for the addresses AO/A7.

The ALE signal on pin 50 of the microprocessor is the control line of the data address latch.

The signal from the revolution and direction of turn sensor (position sensor) in the pump bed is read-in through port T1.

The operation data of the pump is saved in the NOVRAM IC 21 through ports 5.1 to 5.3 when the dialysis machine is switched off or there is a voltage failure. Undervoltage detection (power down) is through the comparitor IC 23.

With the WR line the data takeover for the display is controlled in the external data latch IC 14.

• PLL intermediate circuit

PLL component IC 4 together with the counter IC 19 causes the frequency coming from the processor to control the stepper motor to be multiplied otherwise the processor would be too slow to generate this frequency.

• RISC processor

The RISC processor IC 5 is supplied with a cycle signal from the processor. With each cycle an 8-bit data word is read from a look up table by the processor alternately for each phase of the stepper motor, respectively. Included in this data word is both the current direction as well as the current desired value.

A watchdog for the CPU is also incorporated in the RISC processor. When a cycle is missing on pin 8/IC 5 the RISC processor triggers a reset by the CPU through pin 7.

Display control

The data word for controlling the display is stored in IC 14. The multiplex operation of the individual digits is made possible through the decoder IC 18.

Speed and flow

The speed is transmitted by the processor through port P 1.1 and the flow through port P 1.2 to the dialysis monitor.

Pressure measurement

The differential measurement amplifier for the pressure transducer is formed by the IC 6 (1/2/3) and IC 6 (5/6/7). The measuring signal is read-in by the processor through the AD converter input AN 7 and calibrated for zero and steepness by the software. Afterwards the measuring signal is modulated to pulse width through port P1.3 and transmitted through a subsequent DA converter IC 11 (5/6/7) to the monitor.

4.2.2 Circuit and component layout diagram LP 754 control board HDF

LP 754 Circuit diagram 1/2

LP 754

Circuit diagram 2/2

LP 754

Component layout diagram

4.3 LP 760 HDF motor control

4.3.1 Description

General

The LP 760 serves to control the lift drive.

Lift operation presupposes that the scales are swung away. This is recognized by a limit switch. The scales can be moved upwards or downwards by pressing the \blacktriangle or \blacktriangledown keys. The drive is switched off automatically, likewise by limit switches, when reaching the uppermost or bottommost position. When the scales are being travelled upwards or downwards they can be stopped at any time with the **Stop** key.

The motor for the lift drive is safeguarded against overloading by means of an integrated thermoswitch. If this protection facility responds the lift will come to a standstill. The lift can be used again after the motor has cooled down.

Circuit structure

Supply voltage

The control circuit is supplied with +12 V. This voltage is generated from the +24 V voltage of the hemodialysis machine by the linear controller T1 in conjunction with the capacitors C4, C5 and C6.

Motor control

Two types of circuit are implemented to control the motor:

- a) continuous operation (R21 with components, R22 without components
- b) inching operation for downwards movement (R21 without components, R22 with components).

To Point a):

One D flip-flop is available for each direction of movement (IC 3). The flip-flops are set by a high level on X2/2 (key \blacktriangle) or X2/4 (key \blacktriangledown). The flip-flop for the respective other direction of movement is reset at the same time by pressing the appropriate key. The two flip-flops are reset through high level on X2/3 (**Stop** key). This also takes place should the head of the scales be swung over the machine (high level on X1/6).

To Point b):

There is only one flip-flop available for the upwards movement (IC 3/pin 1/2). The flip-flop for the downward movement is set through IC 5. The control logic for the downward operation is not influenced by this (see Point a). However, the drive is only active as long as the key ▼ is pressed.

The IC 5 works as an 8 to 1 multiplexer. The address (0 to 7) of the input to be interconnected is provided through the pins 11 to 13. Only the address 3 leads to a low level on output IC 5/14 and, as a result, to the motor starting. R 20 serves as a pull-up resistor. A defined output level is obtained with the IC 5/14 in high ohmic state, caused by pressing the **Stop** key (high level on IC 5/15).

• Other circuit sections

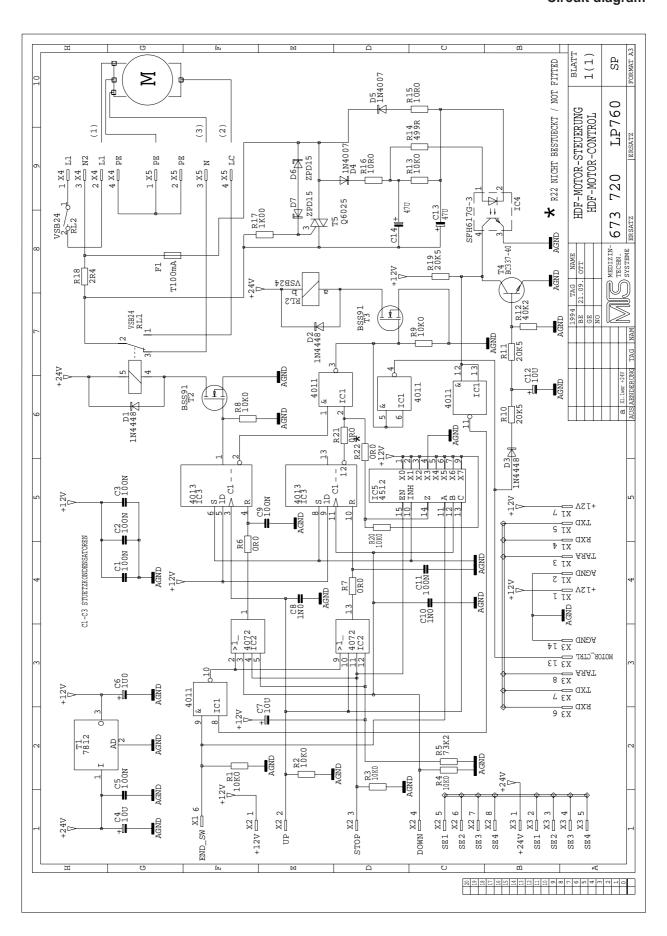
The motor feed lines are circuited through the relay RL 1 and RL 2. The position of RL 1 determines the travel direction of the lift. The motor is switched on and off through RL 2. Both relays are controlled by the transistors T 2 (RL 1) and T 3 (RL 2). T 2 is controlled directly from the non-inverted output IC 3/1. The output signals of both flip-flops, IC 3/2 and IC 3/12 (inverted) are used to control T 3 and are linked with each other through IC 1/1 and IC 1/2. In the case of low level on one of the two flip-flop outputs IC 3/2 or IC 3/13 (i.e. the respective flip-flop has been set) the IC 1/pin 3 links up high level and T 3 switches RL 2.

Motor current recognition

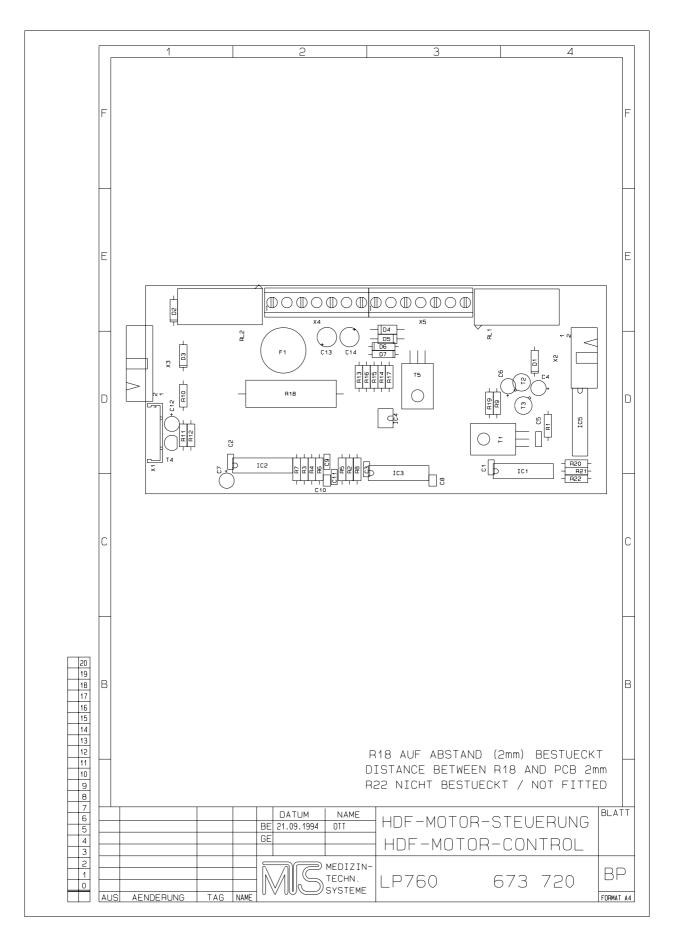
The motor current is monitored while the lift is operating. The internal thermal-protective switch responds in the case of the motor becoming overheated. Both flip-flops (IC 3) are reset by motor current recognition so that the motor does not start up again automatically after the drive has cooled down. The voltage drop is evaluated through the high load resistor R 18 for motor current recognition. The generated alternate voltage caused by the current flow through R 18 is connected to the capacitor C 14 and C 13 through the diodes D 4 and D 5. The resulting direct voltage through R 13 is approx. double so high as the peak value of a half wave of the alternate voltage on R 18 less the on state voltages of D 4 and D 5. The direct voltage controls the optocoupler IC 4 through R 14. R 13 serves to completely discharge C 13 and C 14 when the motor is switched off.

IC 4 ensures protective isolation of the control circuit from the mains voltage conducting components of the current recognition system.

The output of the optocoupler is circuited with the pull-up resistor R 19 against 12 V. High level on the collector of IC 4 resets both flip-flops through IC 1/pin 12 and 13 and IC 1/8. This would lead to continuous blocking of the control circuit unless further measures were taken. This is why the output of IC 4 is connected up parallel to a further transistor T 4. In switched off state the capacitor C 12 is charged through high level on IC 1/4 through D 3 and R 10. This makes the transistor T 4 conductive. After setting one of the flip-flops (IC 3) the IC 1/4 goes to low. C 12 discharges itself through R 11, R 12 and the B-E path from T 4. T 4 blocks after approx. 500 ms. The output transistor must be linked by IC 4 before this time has elapsed otherwise both flip-flops will be reset again.



LP 760
Component layout diagram

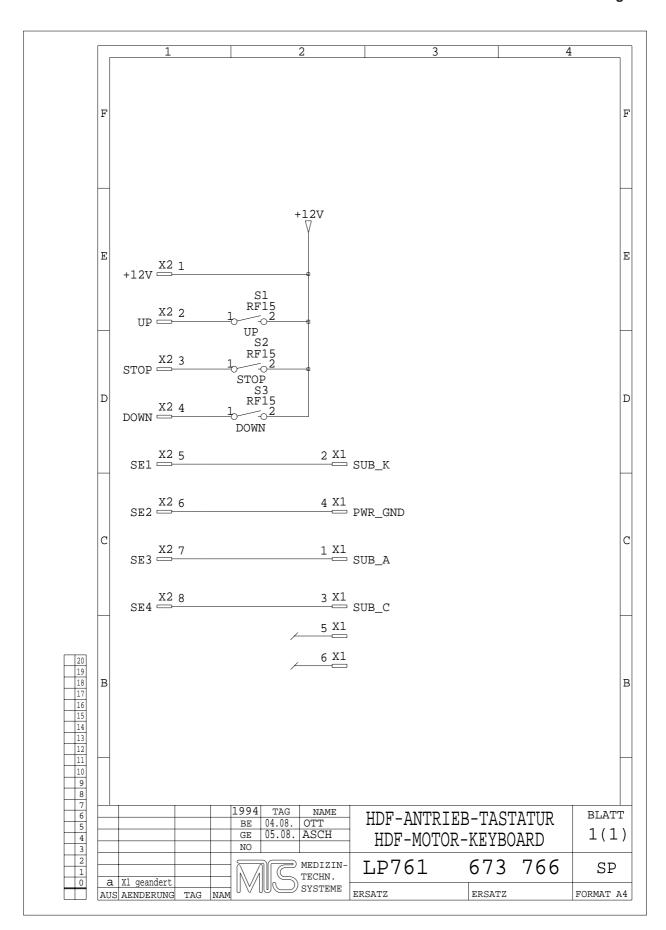


4.4 LP 761 HDF drive keyboard

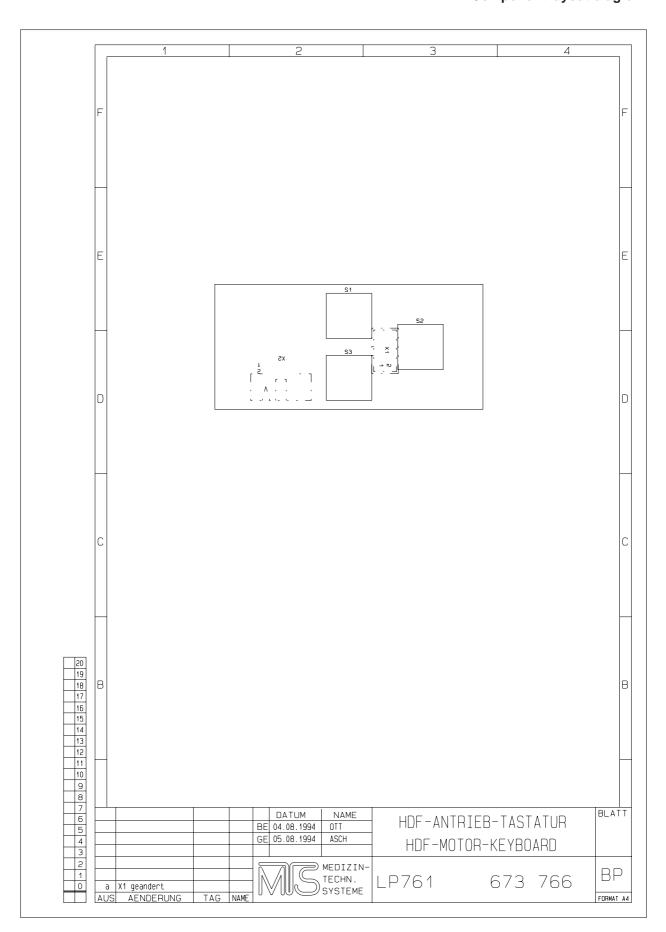
4.4.1 Description

General

The keys for controlling the substituate lift are found on this P.C.B..



LP 761
Component layout diagram



4.5 LP 762 scales comm

4.5.1 Description

The LP 762 serves as interface between the dialysis machine and the scales.

The serial transmission from the dialysis machine arrives on the plug X1 pin 4 (RXD) and is converted at the interface IC 1 (max. 232) to 5 V level. IC 2 makes a serial parallel conversion and passes the signal on to the scales. The scales are switched on or off, respectively, by the transistor T1.

The serial carry forward (weight) comes from the scales to the plug X3 pin 6 (TXD) and is converted by IC 1 from 5 V to RS 232 level. The signal arrives at the dialysis machine through plug X1 pin 5 (TXD).

SP1 (ML78L05) converts the 12 V into 5 V which serves as the supply voltage for LP 762.

LP 762

Component layout diagram

4.6 LP 763 SSE serial interface extender

4.6.1 Description

General

The LP 763 is necessary for serial communication of the monitor with the scales and the HDF pump module.

Circuit structure

The circuit of the LP 763 comprises two circuit units independent of each other.

Serial interfaces

Heart of the LP 763 P.C.B. is an 8-fold UART (universal asynchronous receiver/transmitter), i.e. an interface IC (IC 1) with eight independent serial channels. Also to be found on the P.C.B. are two TTL/RS232 level converters (IC 2 and IC 3) and an interrupt logic IC (IC 4), as well as diverse resistors, capacitors and an oscillation quartz Q1 for generating the working cycle for IC 1.

COMMCO connection

The slot 63Z used by the LP 763 P.C.B. is also provided for the installation of P.C.B. LP 752. The LP 752 takes over the connection of the 4008 monitor signals to the COMMCO P.C.B. LP 729. In order to be able to also continue the linking to COMMCO/FINESSE in 4008 HDF machines the circuit section of the LP 752 P.C.B. is taken over in the LP 763 P.C.B..

Function

After switching on the machine the UART is initialled with the transmission parameters.

Transmission parameter channel A: 1200 Baud, 8 databits, 1 stopbit, no paritibit

Transmission parameter channel B: 9600 Baud, 8 databits, 1 stopbit, no paritibit

Channel A is responsible for communication with the scales, channel B for communication with the HDF pump module.

After going through the watchdog test the scales are switched on through the transmission line from channel A and the weight requirements of the 4008 monitor are communicated to the scales. The weight value of the scales is read by the 4008 monitor on the reception line.

Commands and data from the 4008 monitor are sent through the transmission line from channel B to the HDF pump modules. Data which comes from the HDF pump module is received by the 4008 monitor through the receiving line.

The remaining six communication channels are not used in 4008 operation.

If UART data is ready for collecting or if the transmission buffer is ready to accept new digits during a transmission the component causes an interrupt at CPU 1. CPU 1 processes this interrupt demand (in so far as nothing more important is to be done) and reads a digit from the reception buffer or writes a digit on the transmission buffer.

4.6.2 Circuit and component layout diagram LP 763 SSE serial interface extender

LP 763
Circuit diagram 1/2

LP 763

Circuit diagram 2/2

LP 763

Component layout diagram

Table of contents 5 Spare parts

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5.3	Substituate lift	5-8
5.4	UF2 pump / blood pump (HDF) / valve V126	5-10

5.0 How to use the spare parts catalog

Objective:

Spare parts can be defined and ordered.

Organization:

This spare parts catalogue contains 4 assemblies.

5.1 P.C.B.

5.2 Scales

5.3 Substituate Lift

5.4 UF2 pump / blood pump (HDF) / valve V126

Each assembly has its assembly number. 5.X.0 refers to the basic version. Major changes (modifications) within an assembly can be identified by an increasing decimal (e.g. 5.X.1, 5.X.2, ...)

In the spare part lists it is refered to:

Built-in From Equipment Code To Equipment Code

Update service:

Updates to this spare parts catalog will be released as:

- Replacement pages
- Supplementary pages
- Technical information

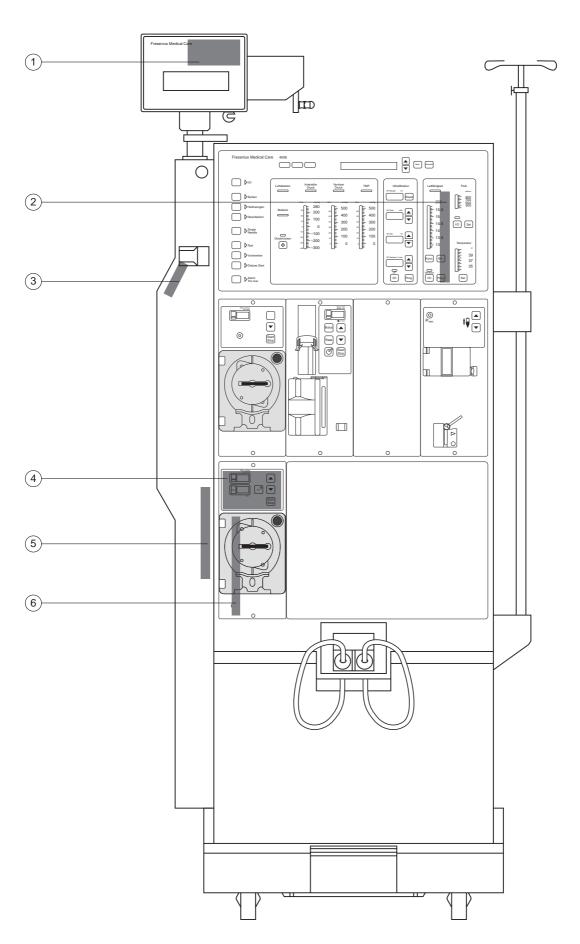
Generally we reserve the right to make changes.

Requirements for correct spare part orders:

The equipment code must be entered in the machine record.

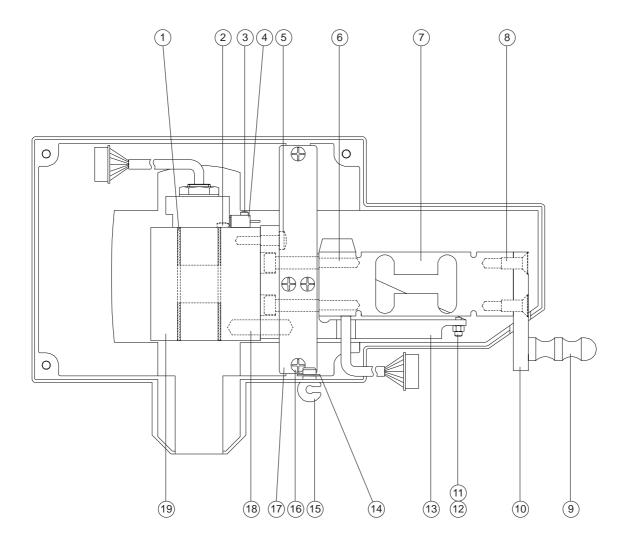
All modifications must be entered in the machine record. Update the equipment code, if necessary, to ensure that the correct spare parts will be ordered.

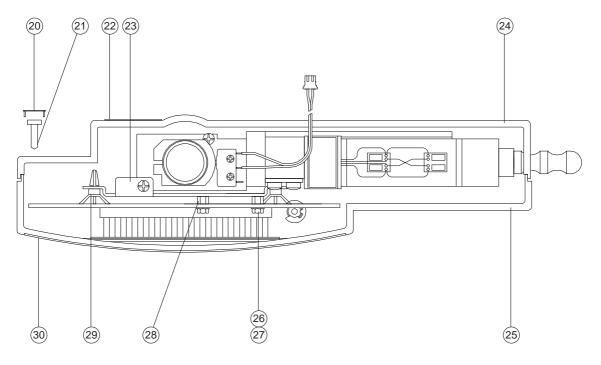
5.1 P.C.B.s



		Built-in From/until Equipment Code	000 – 000
Item	Part number	Description	
1	673 790 1	P.C.B. LP 762 scales comm	
2	674 182 1	P.C.B. LP 763 SEE serial interface extender	
3	673 766 1	P.C.B. LP 761 HDF drive keyboard	
4	673 872 1	P.C.B. LP 625 display board	
5	673 720 1	P.C.B. LP 760 HDF motor control	
6	673 041 1	P.C.B. LP 754 control board HDF	

5.2 Scales



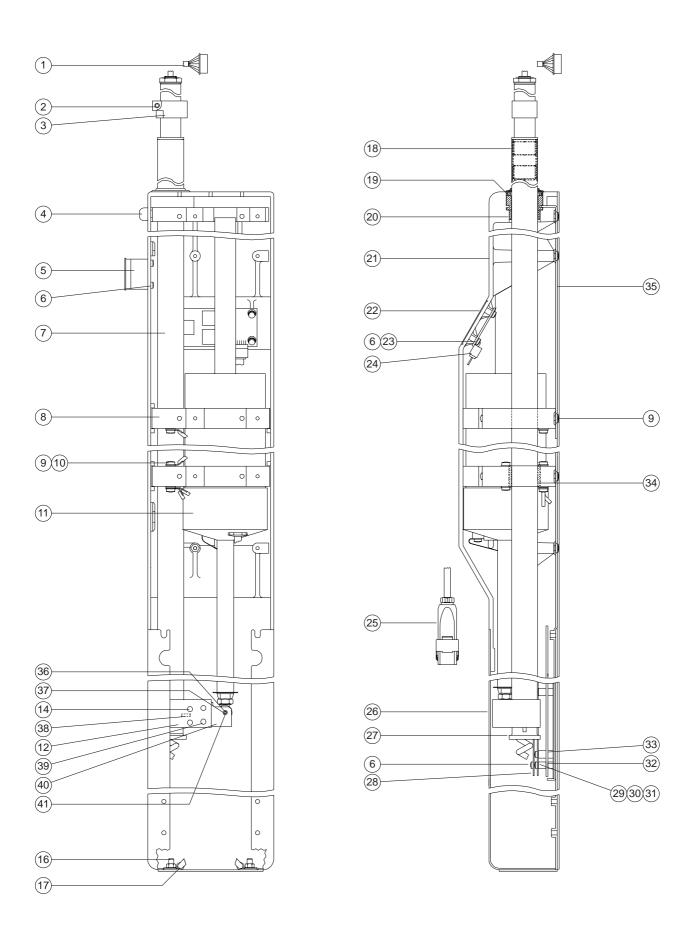


5-6 Fresenius Medical Care 4008 HDF 3/11.97 (TM)

Built-in	
From/until Equipment Code	000 - 000

Item	Part number	Description
1	673 983 1	Sliding bush
2	552 244 1	Screw
3	646 352 1	Screw
4	674 409 1	Microswitch
5	552 312 1	Screw
6 7	553 330 1	Screw
7	673 635 1	System unit, scales
8	643 161 1	Screw
9	673 988 1	Hook
10	673 987 1	Latch
11 12	642 861 1	Screw
12	553 621 1	Nut
13 14	673 986 1	Adapter
	563 151 1	Retaining washer
15	674 106 1	Line holder
16	552 275 1	Screw
17	673 971 1	Fastening plate
18	642 693 1	Screw
19	673 985 1	Bearing
20	672 530 1	Cover
21	552 276 1	Screw
22	674 551 1	Caution label: Stability limit
23	673 977 1	Display plate
24	673 922 1	Back shell
25	673 921 1	Front shell
26	553 620 1	Nut
27	559 690 1	Washer
28	642 648 1	Spacer sleeve
29	640 143 1	Spacer
30	673 923 1	Front foil display
	674 068 1	Scales, complete

5.3 Substituate lift



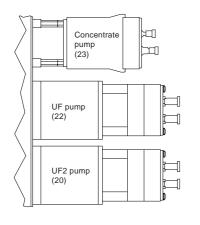
Built-in	
From/until Equipment Code	000 - 000

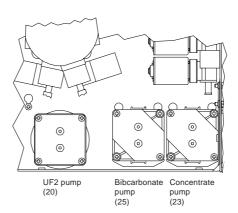
Item	Part number	Description
1	674 399 1	Connection cable
2	644 205 1	Screw
3	673 990 1	Locking ring
4	674 106 1	Line holder
5	653 099 1	Sensor
6	552 244 1	Screw
7	674 334 1	Pipe
8	673 975 1	Clamping plate
9	552 275 1	Screw
10	553 733 1	Toothed washer
11	674 395 1	Drive
12	673 973 1	Dog
14	673 755 1	Screw
16	553 621 1	Nut
17	537 203 1	Fastening clip
18	646 274 1	Tolerance sleeve
19	674 078 1	Stripper
20	673 974 1	Collar bush
21	673 920 1	Housing, lift
22	673 639 1	Front foil, lift
23	559 690 1	Washer
24	674 400 1	Connection cable
25	674 358 1	Connection cable
26	673 918 1	Base plate
27	673 972 1	Funnel
28	674 255 1	P.C.B. cover
29	646 606 1	Spacer bolt (M 3 x 8.5)
30	650 439 1	Spacer bolt (M 3 x 12.5)
31	559 690 1	Washer
32	574 617 1	Spacer sleeve
33	644 040 1	Spacer bolt (M 3 x 13)
34	673 982 1	Bush
35	674 487 1	Sealing tape
36	675 052 1	Split pin
37	553 694 1	Washer
38	674 333 1	Locating pin
39	552 312 1	Screw M5x16
40	675 222 1	Fork
41	675 051 1	Bolt with head
	673 915 1	Substituate lift, complete

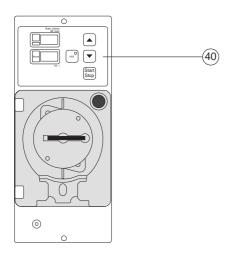
5.4 UF2 pump / blood pump (HDF) / valve V126

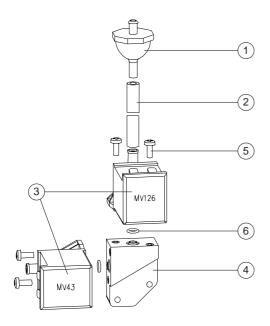
Hydraulic section 4008 / 4008 E

Hydraulic section 4008 B









		Built-in From/until Equipment Code	000 – 000
Item	Part number	Description	
		UF2 pump	
		The UF2 pump is identical with the ultrafiltration pump (see appropriate Spare Parts Catalogue 4008)	
	670 706 1	Ultrafiltration pump, complete	

		Blood pump (HDF)
		The blood pump (HDF) is similar to the blood pump (single needle) (see appropriate Spare Parts Catalogue 4008)
40	671 726 1	Front foil
	673 924 1	Blood pump module HDF, complete

		Valve V126
1	645 881 1	Filter
2	545 361 1	Silicon tube (0.12 m)
3	674 349 1	Solenoid valve MV 126 / solenoid valve MV43
4	674 347 1	Valve block
5	552 275 1	Screw
6	579 072 1	O-ring
	674 941 1	Valve block, complete